

IN THE SPECIFICATION

Please replace the paragraph at page 4, lines 8 to 9, with the following rewritten paragraph:

Q' Figure [1(a)] 1 is a perspective view of a camera according to a first embodiment of the present invention;

Please replace the paragraph at page 11, lines 2 to 7 with the following rewritten paragraph:

Q² When the camera body 10 is inclined at an angle θ toward Ob in the YZ plane as a result of an up-and-down motion of the camera, the output of the acceleration sensor Z1 is acceleration A1 at a distance L1' from Ob, and the output of the acceleration sensor Z2 is acceleration A2 at a distance [L2] L2' from Ob. The accelerations A1 and A2 are described in the following equations (1) and (2). In the equations (1), (2), ω is rotation angular velocity, and t is time.

Please replace the paragraph at page 15, line 23, to page 16, line 3, with the following rewritten paragraph:

Q³ The actuators 53, 54 and position detectors 51, 52 are a part of a mechanical portion for the correction of the camera shaking. The MPU 60 is a part of a controller which drives the actuators 53, 54, 56 according to the acceleration detected by the pairs of acceleration sensors [[Z1, Z2]] Y1, Y2 and X1, X2 in element 240 and position information of each position detector 51, 52, 55.